HEAdas Developer's Guide

Version 1.1

HEASARC
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Chapter 1

Introduction

HEAdas refers to a new component in HEASoft, the LHEA software suite which currently encompasses FTOOLS and XANADU (ie, XSPEC, XRONOS, and XIMAGE). HEAdas tasks are virtually identical in look-and-feel to FTOOLS from a user's perspective but are, in fact, built around a completely distinct core (with the exception of the CFITSIO library). This new package is intended to be simpler and leaner than FTOOLS, as well as more portable, stable and extensible.

HEAdas is composed of two basic parts: a mission-independent set of general FITS utilities (HEAtools) which is being developed within the HEASARC, as well as a set of mission-specific packages developed and maintained (in whole or in part) by outside groups. The HEAdas core (including the HEAtools) is written entirely in ANSI C for maximum portability. Missions are, however, free to use any language they wish within their own package, bearing in mind that certain choices may limit the platforms and/or compilers on which their tasks will build and run.

Until HEAdas has fully matured it is likely that tasks (eg, Perl scripts) in the mission-specific packages will call tasks which still reside in the FTOOLS portion of HEASoft and software distributions by the HEASARC will generally include all necessary components in a single tar file to make things as easy for users as possible. However, in keeping with a modular approach (as well as to avoid incompatibility due to different release schedules) it is important that mission-specific tasks not link against FTOOLS libraries (eg, xanlib). If mission developers find that they require those subroutines in their tasks then they should be migrated to the appropriate HEAdas library. Whether that would be more appropriate to a core library versus a mission-specific library may require coordination and/or consultation with the HEASARC programming staff.

1.1 Configuration Management and HEAdas Setup.

All configuration management of HEAdas will be handled by the HEASARC, including such things as Makefiles and configure scripts. Code revision control will be handled via a central CVS repository resident on HEASARC servers. Developers of mission-specific software will only have write access in the relevant portions of the repository but will have read access to the entire package so that they can check-out as much of it as they wish for local testing. However, a limited number of HEASARC programmers will have global write access to enable necessary configuration mod-

ifications. CVS includes automatic email notification of new check-ins so that developers will be informed of any changes to their portion of the repository as they occur.

The directory structure for any given subpackage will be reasonably flexible so that mission software developers can arrange things to suit their own needs and/or preferences. Certain constraints may, however, be required to accomodate the overall HEAdas build paradigm.

Full, top-down builds are started from the headas/BUILD_DIR directory using the typical steps of ./configure followed by make and then finally make install. Internally, however, builds will be managed by hmake, exactly as in the current FTOOLS package. This utility is designed to also make it easy to build all or part of the distribution on any supported platform without having to make modifications by hand specifying the location and/or names of necessary flags and libraries. That is, once a full build and install have been performed, a developer may simply checkout a copy of a particular tool and build it via the command hmake. Before using hmake (assuming a cshell environment) one simply needs to source the file $HEADAS/BUILD_DIR/hdevinit.csh, where $HEADAS is the environment variable which points to the location of the relevant HEAdas installation, eg, /usr/local/src/headas/i686-pc-linux-gnu. Similarly, to set oneself up to use installed HEAdas tasks one would source $HEADAS/headas-init.csh. Note that Bourne shell/bash variants are also provided for people who prefer those shell environments. These are identical except that the file suffixes are .sh instead of .csh and they would, of course, be invoked according to the usual shell syntax.

NOTE: For the time being the hmake utility from a HEASoft installation is NOT interchangable with the one from a HEAdas installation. This is currently being revised and ultimately it will not matter which version comes first in one's search path. Until then, caveat developer...

1.2 Input and Output

1.2.1 Input

All input to HEAdas tasks is controlled by the Parameter Interface Library (PIL) which is developed and maintained by the INTEGRAL Science Data Center. PIL has a very similar look and feel to XPI (the parameter interface used in FTOOLS) but includes such additional features as enumerated values, minimum-maximum range checking, the ability to use environment variables in parameters and a dedicated "filename" type. PIL is callable by C, C++, f77 and f90 tasks. Full documentation for PIL is available in the source tree under headas/heacore/pil/doc.

There are three commonly-used parameters which are handled intrinsically by the internal HEAdas initialization routines and thus developers do not need to explicitly read them at the individual task level. (A fourth parameter, "mode", is a PIL internal and operates exactly as in XPI). The standard HEAdas parameters are:

- CHATTER The (integer) "chatter" parameter may be used to control the verbosity of a HEAdas task. (This is similar to the "verbose" parameter used in CIAO, however, since a number of FTOOLS tasks, especially in the caltools subpackage, use "chatter" we have chosen to keep the same name for consistency across the HEAsoft suite.) Developers are free

to specify any range (via the parameter min/max) but we recommend the following (0-5):

0 suppresses all but absolutely essential output

1-4 normal levels. The different levels can be used on a task by task basis to control the amount of output information. The distinction between the different chatter levels (if any) must be documented in the task's help file. For many tasks, all 4 chatter levels might produce exactly the same output.

5 debug mode: prints detailed messages about each step in the program

The desired chatter value will be specified by the user at runtime and read automatically during the initialization phase. The task developer may then funnel diagnostic output through the supplied routines (see output section below) which take as their first argument a threshold chatter level below which the output will be suppressed. A chatter parameter is not required for any task, however, calling headas_chat()/hdchat() in a task having no chatter parameter will result in an error.

- CLOBBER

  If a (boolean) "clobber" parameter is present for a given task it will be read during the initialization phase. Developers may then call headas_clobberfile(filename) which will delete the specified file if it exists and if the "clobber" parameter was set to "yes". Note that an alternative to clobber exists for FITS files since CFITSIO will clobber any file which begins with the "!" character.

- HISTORY

  The (boolean) "history" parameter controls whether or not the user wishes to allow a set of HISTORY keywords listing the runtime values of all task parameters to be written into any FITS file header. The developer simply calls HDpar_stamp() specifying the desired FITS file and extension and, if the history parameter value at runtime permits it, the HISTORY block will be written. If the task has no history parameter then a call to HDpar_stamp() will return an error. Each HISTORY keyword block will be clearly delimited and will include the task name/version and a timestamp. Use of HDpar_stamp() is not required, but is recommended both as a means of documenting the runtime conditions and as input for a planned utility which can rerun any task using the information recorded in the HISTORY block.

1.2.2 Output

Diagnostic output and other text messages must be able to be separated from the standard output stream to enable, eg, piping FITS files between tasks. Developers should never write directly to stdout but should instead funnel screen output through the dedicated HEAdas streams. These streams are set up during task initialization and are controlled by environment variables. Task developers should never have to read or otherwise deal with these variables. The following methods for diagnostic output are currently available to developers writing tasks in C:

headas_printf(char *, ...) Operates exactly like the stdio version of printf but the stream will be directed to the location specified by the environment variable HEADASOUTPUT (if present).

headas_chat(int, char *, ...) Identical to headas_printf() except for an additional integer argument which specifies the threshold "chatter" level below which the message will be suppressed (depending on the runtime value of the chatter parameter, see discussion of "chatter" above).

fprintf(heaout, char *, ...) The "heaout" stream (which replaces stdout in HEAdas) may be written to directly, as shown.

printf(char *, ...) The usual stdio printf() routine can still be used (eg, in legacy code) but will be dynamically replaced by headas_printf() during compilation.

Fortran tasks should use the dedicated routines hdecho() and hdchat(). The former is exactly equivalent to the fcecho() routine in the FTOOLS package while the latter adds the chatter threshold argument as in headas_chat() above. Note that unlike the C versions above, formatting of the output strings must be done prior to calling hdecho()/hdchat(), eg, via an internal write.

Future GUI development and/or other enhancements to HEAdas will likely require that the standard error stream and parameter prompts be monitored and/or redirected as well. The environment variables HEADASERROR and HEADASPROMPT, respectively, control these but developers should not need to deal with them directly. C tasks may simply use fprintf(stderr, ...) to print error messages as usual, while Fortran tasks should use hderr() (which is exactly like the FTOOLS fcerr() routine). As with hdecho(), the output error message must be constructed internally prior to calling hderr().

1.3 General Notes

All tasks should:

- Follow ANSI standards (ie, C89 and X3J3/90.4 for C and Fortran77, respectively) for maximum portability.
- Be written as a subprogram (not a main) which returns an integer status value.
- (for C only) Contain the following block of code near the top of the task subroutine:

```
#include "fitsio.h" /* assuming CFITSIO routines will be called */
#include "pil.h" /* assuming PIL routines will be called */
#include "headas.h"

#define TOOLSUB my_task_subroutine_name /* use actual subroutine name here */
#include "headas_main.c"
```

- Check return status after all CFITSIO and PIL calls and use the relevant error reporting routine if status is non-zero.
- Register a task name and version number (see below).

1.4 Task Name and Version

Every HEAdas task should register its name and version number so that the information is available to other routines which may need it. A set of routines in the heautils library (see headas_toolname.c in the library inventory section, below) has been provided for this purpose. Each task should call set_toolname() and set_toolversion() to record the information and developers may retrieve the information via get_toolname()/get_toolversion() or by the simpler get_toolnamev() which returns both in a single string with name and version joined with an underscore. The Fortran equivalents are hdnameset(), hdverset(), hdnameget(), hdverget() and hdnamevget(). Note that a default name is recorded during task initialization based on the executable name. A default version number of "0.0" will likewise be used. These defaults will be superceded via calls at the task level to set_toolname() and set_toolversion().

1.5 CALDB Access

The HEASARC Calibration Database (CALDB) will be accessible to HEAdas tasks exactly as it is to FTOOLS and missions choosing to use HEAdas should plan on submitting their FITS calibration files for inclusion in the CALDB. However, because the main CALDB access routine, gtcalf(), is written in f77, however, it is being rewritten in ANSI C in keeping with the requirements of the HEAdas core. The method in which it is used will be exactly the same, making code migration from the FTOOLS system trivial. As in most of the routines discussed here, a Fortran wrapper will be provided so that they may be called from Fortran tasks too.

1.6 Scripting

All scripting should be done using Perl5. The HEASARC will provide Perl utilities to make it easy and convenient for scripts to call HEAdas and/or FTOOLS tasks, for example, to trap any runtime errors which may occur. We also expect to include the CFITSIO Perl module (CFITSIO.pm) in the distribution to allow for Perl scripts to directly call CFITSIO routines as well.

1.7 Expected Enhancements

In addition to the components already mentioned, the following are being evaluated for inclusion with the HEAdas package:

- CCfits: an object-oriented interface to the CFITSIO library designed to make the capabilities of CFITSIO available to programmers working in C++.

Chapter 2

Overview of HEAdas Libraries

The "heacore" directory contains source code for a number of libraries which are expected to be generally useful and mission-independent. These core libraries will automatically be built and available for linking by any or all of the tool packages (eg, heatools, swift) via the normal hmake build process. Some of these libraries are developed at the HEASARC, while others are external packages which are simply redistributed as part of HEAdas. Documentation for each library component may be found under the directory containing that component.

The software components of the directory "heacore" are:

- cfitsio: a standard FITS file I/O library developed at the HEASARC. http://heasarc.gsfc.nasa.gov/docs/softw
- pil: an IRAF-style parameter interface library, developed for the INTEGRAL mission at the Integral Science Data Center (ISDC). http://isdc.unige.ch
- readline: a standard input library which supports shell-style tab completion and command recall functions. http://cnswww.cns.cwru.edu/php/chet/readline/rltop.html
- atFunctions: library of attitude-related routines developed at the Institute of Space and Astronautical Science (ISAS).
- coord/coordfits: additional routines for attitude, coordinate transformations, etc.
- Astro-FITS-CFITSIO: a CFITSIO Perl module, distributed by Pete Ratzlaff (CfA). http://hea-www.harvard.edu/ rpete/cfitsio
- heainit: HEAdas Initialization functions callable at global scope
- heaio: HEAdas Input/output library
- heautils: Assorted HEAdas utilities
- heasp: HEAdas utilities for spectra and responses

More detailed documentation for the last four (HEAdas native) libraries follows below.

2.1 heainit

- `headas.h`

  Header file containing function prototypes, etc.

- `headas_init.c`

  Contains routines called internally – developers should not ever need to call these explicitly:

  - `int headas_init(int, char **)`

    Calls routines to initialize PIL and output streams. It also deals with standard HEAdas parameters (chatter, clobber, history).

  - `int headas_close()`

    Closes output streams and PIL.

  - `int hdIOInit()`

    Checks environment variables (eg, HEADASOUTPUT, HEADASERROR) and sets up output streams.

  - `int hd_pil_err_logger(char *s)`

    Default PIL error logging routine. Simply prints to stderr.

- `headas_main.c`

  This file comprises the main program unit for every task. It calls headas_init() followed by the task subroutine itself and then calls headas_close() after the task completes. This main routine is not part of any library and must be explicitly included by all C tasks (via #include "headas_main.c"). For f77 tasks it is automatically compiled and linked in by the Makefile.

2.2 heaio

- `headas_stdio.c`

  Contains routines used to write diagnostic and error output to the standard HEAdas output/error streams (replacing C stdio routines):

  - `int headas_printf(const char *, ...)`

    Replaces the stdio printf() with identical arguments. Text is written to the location specified by the HEADASOUTPUT environment variable (if present) instead of to stdout.

  - `int headas_chat(int, const char *, ...)`

    Same as headas_printf() but takes an integer argument which specifies the threshold chatter level below which the text will not be output.

  - `int pil_printf(const char *, ...)`

    A substitute for printf() for internal use by PIL only. Should not be called by tasks directly. NOT CURRENTLY USED.

- `void headas_f77echo(const char *)`

  A f77-callable version of headas_printf(). It is called hdecho() from Fortran programs.

- `void headas_f77err(const char *)`

  A f77-callable version of fprintf(stderr, ...). Called hderr() from Fortran. This routine will write to the stderr stream (which may have been redirected via the HEADASERROR environment variable).

- `void headas_f77chat(int, const char *)`

  A f77-callable version of headas_chat(). It is called hdchat() from Fortran.

2.3 heautils

- `headas_utils.c`

  Contains utility routines:

  - `int headas_parstamp(fitsfile *, int)`

    Writes a block of HISTORY keywords into a FITS file header listing all the runtime parameter values. Arguments are a FITS file pointer and extension number. Callable from Fortran as hdparstamp(). *** DEPRECATED *** PLEASE USE HDpar_stamp (see below) INSTEAD ***

  - `int HDpar_stamp(fitsfile *, int, int *)`

    Writes a block of HISTORY keywords into a FITS file header listing all the runtime parameter values. Arguments are a FITS file pointer, extension number, and status pointer. Callable from Fortran as hdpar_stamp().

  - `char *hdbasename(char *)`

    Equivalent to the basename() function (returns the filename portion of an input pathname).

  - `int headas_clobberfile(char *)`

    Deletes the specified file if it already exists and if the clobber parameter for the current task is set to "yes". Callable from Fortran as hdclobber().

  - `float hd_ran2(long *)`

    Random number generator based on ran2() from Numerical Recipes in C, 2nd ed., p282. Returns a uniform random deviate between 0.0 and 1.0 (exclusive of the endpoint values). Call with a negative integer argument to initialize. Callable from Fortran as hd_ran2().

- `headas_toolname.c`

  Contains routines to get/set the name/version of the current task:

  - `void set_toolname(const char *)`

    Use this to register the task's name. The Fortran version is hdnameset().

- `void get_toolname(char *)`

  Use this to retrieve the task's name. If it hasn't been set (via set_toolname()) a default name is determined from the name of the executable file. The Fortran version is hdnameget().

- `void set_toolversion(const char *)`

  Use this to register a version number string for a task. The Fortran version is hdverset().

- `void get_toolversion(char *)`

  Use this to retrieve a string containing the task's version number. If it hasn't been set (via set_toolversion()) a default version number string of "0.0" is returned. The Fortran version is hdverget().

- `void get_toolnamev(char *)`

  Use this to retrieve a single string containing both the task's name and version number (joined by a "_"). The Fortran version is hdnamevget().

- `headas_history.c`

  Contains routines to get/set the value of the history parameter. Designed primarily for internal use and under normal circumstances should not be called by tasks explicitly.

  - `void get_history(int *)`

    This routine returns the value of the history parameter (if present) or "-1" if unspecified. Called by headas_parstamp(). Fortran version is hdghis().

  - `void set_history(int)`

    This registers the value of the history parameter. If it is called explicitly from a task it will override the user-specified value. Fortran version is hdphis().

- `headas_copykeys.c`

  Contains routine to copy non-critical keywords from one HDU to another..

  - `int HDcopy_keys(fitsfile *inptr, fitsfile *outptr, int docomments, int dohistory, int`

    Both the input and output FITS files should be positioned at the correct HDU. If docomments is true then COMMENT records will be copied and if dohistory is true then HISTORY records will be copied.

- `headas_polyfit.c`

  Contains routine to do a least-square polynomial fit.

  - `void HDpoly_fit(double * x, double * y, double * c, int n, int degree)`

    where x is the input n-element array of independent variables, y is the input n-element array of dependent variables, degree is the degree of the polynomial, and c is the output degree+1-element array of coefficients.

- `headas_sort.c`

  Contains routine to do a quick sort on the input array, returning sorted index (instead of data as with C qsort).

  - `void HDsort(float * base, int * index, int n)`
    where base is the input n-element unsorted data array and index is the input/output n-element array index.

- `headas_smooth.c`

  Contains routine to do a boxcar average on input data:

  - `void HDsmooth(float * input, float * output, int num, int width)`
    where input is the num-element unsmoothed array, output is the num-element smoothed array, and width is the width of the boxcar.

- `headas_svdfit.c`

  Contains routines used by HDpoly_fit (slightly modified versions of routines from Press, William H., Brian P. Flannery, Saul A Teukolsky and William T. Vetterling, 1986, "Numerical Recipes: The Art of Scientific Computing" (Fortran), Cambridge University Press.

- `headas_rand.c`

  Contains routines to generate (0,1) uniformly distributed pseudo-random numbers.

  - `void HDmtInit(unsigned long int seed)`
    Initialize the algorithm. Must be called first.
  - `void HDmtFree()`
    Clear the algorithm.
  - `double HDmtRand()`
    Return a pseudo-random number.

2.4 heasp

- `MergeARFRMF.c`

  Contains routine to multiply an ARF and an RMF.

  - `long MergeARFRMF(struct ARF *arf, struct RMF *rmf)`
    Multiplies the ARF and RMF structures and returns the result in the RMF structure. If there is a mismatch between energy bins returns the first inconsistent bin number.

- `RMF.c`

  Contains RMF manipulation routines.

  - `void RMFCompressLine(float *Vector, long VectorLength, float Threshold, long CurrentGroup, long CurrentElement, long *GroupStart, long *GroupSize, long *GroupFirstElement, long *NumberGroups, float *MatrixElements, long *NumberElements)`

    Compress the vector representation of the response for a single energy and add into the RMF.

  - `void RMFExpandLine(long *GroupStart, long *GroupSize, long *GroupFirstElement, long NumberGroups, long FirstGroup, float *MatrixElements, long VectorLength, float *Vector)`
    Extract from the RMF the vector representation of the response for a single energy.
  - `float ReturnRMFElement(struct RMF *rmf, long channel, long energybin)`
    Return the RMF element for the input channel and energy bin.
  - `float ReturnRMFchanElement(struct RMFchan *rmfchan, long channel, long energybin)`
    Return the RMF element for the input channel and energy bin when the RMF is stored in the transposed RMFchan structure.

- `ReadARF.c`

  Contains routine to read an ARF.

  - `int ReadARF(fitsfile *fptr, long ARFnumber, struct ARF *arf)`
    Read an ARF from the SPECRESP extension in the opened FITS file. If there are multiple SPECRESP extensions will read the ARFnumber one.

- `ReadPHA.c`

  Contains routine to read a PHA file.

  - `int ReturnPHAtype(fitsfile *fptr, long PHAnumber)`
    Return either 1 or 2 depending on whether the PHAnumber'th SPECTRUM extension is a type 1 or 2 PHA type.
  - `long ReturnNumberofSpectra(fitsfile *fptr, long PHAnumber)`
    Return the number of spectra in the PHAnumber'th SPECTRUM extension in the opened file.
  - `int ReadPHAtypeI(fitsfile *fptr, long PHAnumber, struct PHA *pha)`
    Read the PHAnumber'th SPECTRUM extension into the PHA structure. Assumes the file is opened but not necessarily positioned at the correct extension.
  - `int ReadPHAtypeII(fitsfile *fptr, long PHAnumber, long NumberSpectra, long *SpectrumNumber, struct PHA **pha)`
    Read the PHAnumber'th SPECTRUM extension. Reads the spectra specified by the SpectrumNumber array into an array of PHA structures.

- `ReadRMF.c`

  Contains routines to read the RMF file.

  - `int ReadRMFMatrix(fitsfile *fptr, long RMFnumber, struct RMF *rmf)`
    Read the RMFnumber'th MATRIX (or SPECRESP MATRIX) extension into a RMF structure.
  - `int ReadRMFEbounds(fitsfile *fptr, long EBDnumber, struct RMF *rmf)`
    Read the EBDnumber'th EBOUNDS extension into a RMF structure.

- `ReturnChannel.c`

  Routine to return a channel given an RMF and an input energy.

  - `void ReturnChannel(struct RMF *rmf, float energy, int NumberPhoton, long *channel)`
    Return NumberPhoton channel numbers from the input energy by drawing randum numbers from a distribution derived from the RMF.

- `SPio.c`

  Internal I/O routines mainly to provide transparent handling of keywords which may be columns in type II PHA files.

  - `int SP_read_key(fitsfile *fptr, int datatype, char *keyword_name, void *keyword_value, void *keyword_default)`
    Read keyword_name of type datatype into keyword_value.
  - `int SPII_read_key(fitsfile *fptr, int datatype, char *keyword_name, long ispec, void *keyword_value, void *keyword_default)`
    Read keyword_name or type datatype into keyword_value from a type II file. Looks first for a keyword of the requested name then if ispec ¿ 0 for an entry in a column.
  - `int SP_read_col(fitsfile *fptr, int datatype, char *column_name, long number_values, void *column_values)`
    Read column_name of type datatype into column_values.
  - `int SPII_read_col(fitsfile *fptr, int datatype, char *column_name, long ispec, long number_values, void *column_values)`
    Read column_name of type datatype into column_values. Will read either from a keyword, a column, or a vector element of a column as appropriate.
  - `int SP_write_key(fitsfile *fptr, int datatype, char *keyword_name, void *keyword_value, char *comment)`
    Write keyword_value to keyword_name.
  - `int SPII_write_key(fitsfile *fptr, int tfields, char *ttype[], int datatype, char *keyword_name, void *keyword_value, char *comment)`
    Write keyword_value to keyword_name unless it is a column.
  - `int SP_need_col(void *array, long array_size, int datatype)`
    Returns true if not all elements of array are the same value.
  - `int SPII_set_table_str(char *column_name, char **column_values, long number_values, int *tfields, char *ttype[], char *tform[], char *tunit[])`
    Check whether the array of strings in column_values are all the same. If not set the table parameters and increment the tfield counter.
  - `int SP_write_col(fitsfile *fptr, int datatype, char *column_name, int *colnum, long nrows, void *column_values)`
    Writes column_values to column_name unless all the values are the same in which case write to a keyword. If a column is written the colnum is incremented.

  - `int SPII_write_col(fitsfile *fptr, int tfields, char *ttype[], int datatype, char *column_name, int rownum, long vector_length, void *column_values)`
    Write column_values as a vector element in column_name.

- `SPutils.c`

  Internal utility routines for the heasp library.

  - `int SPReadBinningFile(char *filename, struct BinFactors *binning)`
    Read an ascii file of binning factors into the BinFactors structure.
  - `int SPSetGroupArray(int inputSize, struct BinFactors *binning, int *grouping)`
    Sets up a grouping array using the information in the BinFactors structure. Assumes that the grouping array has been allocated enough memory, that the binning ranges are contiguous, the start channel of a range is the channel after the end channel of the previous range, and that the first channel is 1.
  - `int SPBinArray(int inputSize, float *input, int *grouping, int mode, float *output)`
    Bin the input array up using the grouping data to create the output array. Mode takes four values : 1 means sum bins, 2 take the mean, 3 return the value of the first channel in the bin, and 4 return the value of the last channel in the bin.

- `TransposeRMF.c`

  Routine to transpose the RMF matrix.

  - `void TransposeRMF(struct RMF *rmf, struct RMFchan *rmfchan)`
    Transpose the matrix in the RMF structure and output in the RMFchan structure.

- `WriteARF.c`

  Routine to write an ARF.

  - `int WriteARF(fitsfile *fptr, struct ARF *arf)`
    Write the ARF structure to the output FITS file. Assumes the file is open and creates a new SPECRESP extension.

- `WritePHA.c`

  Routines to write the PHA file.

  - `int WritePHAtypeI(fitsfile *fptr, struct PHA *pha)`
    Write the PHA structure to the output FITS file. Assumes the file is open and creates a new SPECTRUM extension.
  - `int WritePHAtypeII(fitsfile *fptr, long NumberSpectra, struct PHA **pha)`
    Write the array of PHA structures to the output FITS file. Assumes the file is open and creates a new type II SPECTRUM extension.

- `WriteRMF.c`

  Routines to write the RMF file.

  - `int WriteRMFMatrix(fitsfile *fptr, struct RMF *rmf)`
    Write the MATRIX extension to the output FITS file. Assumes the file is open and creates a new extension.
  - `int WriteRMFEbounds(fitsfile *fptr, struct RMF *rmf)`
    Write the EBOUNDS extension to the output FITS file. Assumes the file is open and creates a new extension.

Chapter 3

HEAdas Makefiles

3.1 Introduction

HEAdas Makefiles are designed so that the most common steps needed to build and install software can be accomplished with minimal effort, but the flexibility exists to override and extend standard behavior. This is accomplished by including a "standard Makefile" in every HEAdas Makefile. In this way, developers can perform most functions simply by filling in definitions for a standard set of macros before the standard Makefile is included. Most of the time, there is no need to add explicit targets. In fact, explicit targets should be avoided whenever possible because it increases the possibility for breakage if/when the standard Makefile is changed.

Before giving a full exposition of all the features available through the standard Makefile, it will be useful to give a simple example. The most common situation for a developer is that he/she would like to add a new standalone compiled task to an existing (probably mission-specific) component. If this is the reader's need, understanding this example should suffice, and there will be no need for a deeper understanding of the more general options which are available.

3.2 Simplest case: A Makefile for a single task

Suppose one wishes to build a task called sample for the swift mission from the files sample1.c and sample2.c. This task has a help file called sample.html, and a parameter file called sample.par. Furthermore, this task has a unit test in the form of a perl script named ut-sample, which produces a FITS file ut-sample.fits. The following Makefile would supply all the necessary targets and macros to make the task behave (build, install, clean, test, etc.) like all other HEAdas tasks:

```
# Component (mission) name. Developers need not change/delete this.
HD_COMPONENT_NAME = swift

# Software release version number. Developers need not change/delete this.
HD_COMPONENT_VERS =
```

```
# If this directory needs to build a task, list its name here.
HD_CTASK = sample

# C language source files (.c) to use for the task.
HD_CTASK_SRC_c = sample1.c sample2.c

# C flags to use in every compilation.
HD_CFLAGS = ${HD_STD_CFLAGS}

# Library flags to use when linking C task.
HD_CLIBS = ${HD_STD_CLIBS}

# Task(s) to be installed.
HD_INSTALL_TASKS = ${HD_CTASK}

# Help file(s) to install.
HD_INSTALL_HELP = ${HD_CTASK}.html

# Parameter file(s) to install.
HD_INSTALL_PFILES = ${HD_CTASK}.par

# Perl unit test script(s) to install.
HD_TEST_PERL_SCRIPTS = ut-sample

# Extra item(s) to remove during a clean or distclean.
HD_CLEAN = ut-sample.fits

# Include the standard HEADAS Makefile to do the real work.
include ${HD_STD_MAKEFILE}
```

Note that, as in all UNIX Makefiles, macro definitions must start at the beginning of a line, with no whitespace of any kind before the macro name.

This Makefile will in effect provide the following targets, which will have the stated behaviors:

- default: Build each source file to produce an object file, then link the object files to create the compiled task. This is also the target which will be "maked" if one invokes make with no explicit target.
- all: Perform the same actions as the default target, and in addition, "publish" the compiled task into the local "build" area.
- clean: Remove all object files and other build by-products, as well as the FITS file created by the unit test script.
- distclean: Remove the compiled task as well as the items removed by the clean target.

- install: Install the compiled task into the proper destination in the "installed" location.
- install-test: Install the test script into the proper destination in the "installed" location.

In general the best way to create a new Makefile for a directory is to copy a Makefile from the most similar example possible. This way, if there are component-specific features which are present in one component's Makefiles and not others, the new Makefile will remain as similar as possible to others in its same component group. In other words, when starting a new task for the SWIFT mission, start with another SWIFT task Makefile. For a new library for ASTRO-E2, start with an existing ASTRO-E2 library Makefile, etc.

3.3 Standard Macros

Most if not all actions a Makefile needs to perform can be controlled entirely by setting one or more standard macros. In general, defining a macro to have a (non-trivial) body enables a particular behavior, while omitting a macro or defining it to have a trivial body (i.e. an empty definition) disables that behavior. This way, a single Makefile can in principle control many distinct bulid actions. Note that it is not always a good idea to structure Makefiles this way, but this flexibility exists to allow individual mission teams to lay out their directories in the way they choose.

3.3.1 Macros Pertaining To All Build Actions

- HD_CFLAGS: Compiler flags used in every C compilation, regardless of whether the object file is included in a library or a task. Usually this should be defined to be equal to ${HD_STD_CFLAGS}, which is set by hmake to be the correct flags for the current component, architecture and compiler.
- HD_CLIBS: Flags specifying the libraries in the link line for tasks linked with C. This includes path information (-L flags) to find the libraries as well as the library names themselves (-l flags). Usually this should be defined to be equal to ${HD_STD_CLIBS}, which is set by hmake to be the standard C link information for the given software component.
- HD_CXXFLAGS: Compiler flags used in every C++ compilation, regardless of whether the object file is included in a library or a task. Usually this should be defined to be equal to ${HD_STD_CFLAGS}, which is set by hmake to be the correct flags for the current component, architecture and compiler.
- HD_CXXLIBS: Flags specifying the libraries in the link line for tasks linked with C++. This includes path information (-L flags) to find the libraries as well as the library names themselves (-l flags). Usually this should be defined to be equal to ${HD_STD_CXXLIBS}, which is set by hmake to be the standard C++ link information for the given software component.

Linking Fortran 77 code with C or C++ usually requires some additional libraries to be included at link time. The macro ${F77LIBS4C} is defined by hmake to hold this information for the current

architecture and compiler. If Fortran 77 code is involved in a task, it may be necessary to add this macro to the definition of HD_CLIBS and/or HD_CXXLIBS. Of course, if this ends up being a component-wide requirement, it is also possible for hmake to include the contents of the F77LIBS4C macro directly in HD_STD_CLIBS and/or HD_STD_CXXLIBS.

3.3.2 Macros Pertaining To Tasks

The standard Makefile provides direct support for building tasks which have source files in C, C++, and/or Fortran 77. In principle a task may arbitrarily blend these languages.

At present, it is required that a C or C++ "main" function be used, rather than a Fortran 77 "program" statement. Consistent with this is the fact that the standard Makefile only supports linking using a supported C or C++ compiler. This is controlled with two families of macros. The first family controls tasks which are linked with C:

- HD_CTASK: The name of the executable which will be produced.
- HD_CTASK_SRC_c: A list of C source files with the suffix .c.
- HD_CTASK_SRC_f: A list of Fortran 77 source files with the suffix .f.

Note that there are no macros associated with C++ in this group. This is because if C++ code is mixed with C, it is required that the task be linked with a supported C++ compiler. Tasks linked with the C++ compiler are controlled with a second family of macros:

- HD_CXXTASK: The name of the executable which will be produced.
- HD_CXXTASK_SRC_C: A list of C++ source files with the suffix .C.
- HD_CXXTASK_SRC_cc: A list of C++ source files with the suffix .cc.
- HD_CXXTASK_SRC_cpp: A list of C++ source files with the suffix .cpp.
- HD_CXXTASK_SRC_cxx: A list of C++ source files with the suffix .cxx.
- HD_CXXTASK_SRC_c: A list of C source files with the suffix .c.
- HD_CXXTASK_SRC_f: A list of Fortran 77 source files with the suffix .f.

For C and Fortran 77 source files, it is a very widespread convention to use .c and .f as the suffix, respectively. For C++ a number of different conventions are in use, which is why there are a number of macros whose names are distinguished by the suffix of the source files each macro includes.

If the HD_CTASK macro is defined, the HD_CTASK_SRC_c macro must contain at least one source file. If the HD_CXXTASK macro is defined, at least one of the HD_CXXTASK_SRC* macros which contain C or C++ source files must contain at least one source file.

When one or both of these macro families are properly defined, the standard Makefile will build the task(s) as part of the default target. First, all the source files in all the macros will be compiled, using the flags specified in the relevant HD_*FLAGS macro. Then the resulting object files will be linked to the libraries specified in the relevant HD_*LIBS macro.

3.3.3 Macros Pertaining To Libraries

The standard Makefile provides direct support for building shared and/or static libraries which have source files in C, C++ and/or Fortran 77. The following family of macros controls this process:

- HD_LIBRARY_ROOT: The root name of the library, without the prefix lib and without any suffix. For example, to build libmylib.so this macro would be simply mylib.
- HD_LIBRARY_SRC_c: A list of C source files with the suffix .c.
- HD_LIBRARY_SRC_C: A list of C++ source files with the suffix .C.
- HD_LIBRARY_SRC_cc: A list of C++ source files with the suffix .cc.
- HD_LIBRARY_SRC_cpp: A list of C++ source files with the suffix .cpp.
- HD_LIBRARY_SRC_cxx: A list of C++ source files with the suffix .cxx.
- HD_LIBRARY_SRC_f: A list of Fortran 77 source files with the suffix .f.

At least one of the source macros must contain at least one file if the HD_LIBRARY_ROOT macro is defined. With these macros properly defined, the standard Makefile will build the library as part of the default target. First all the source files listed in the source macros will be compiled, then they will be placed into the relevant shared or static library.

3.3.4 Macros Pertaining To Installation

Another family of macros determine which items will be installed during the "install" step. For maximum flexibility, no items are ever installed automatically. In order to install say a binary which was built by the current Makefile, it is necessary to list that binary explicitly in the list of binaries to install. In addition, a variation on install, called publish, is supported, in which items will be installed into the local build area by the "all" target, but not installed into the final installed area given by the configure prefix. The macros which control installation are:

- HD_INSTALL_EXTRA: Explicit targets which will be "maked" at install time, which take custom actions which do not fit into any category. This should be used sparingly.
- HD_INSTALL_HEADERS: C and/or C++ header files to be installed into the top-level include/ directory. Not every header file necessarily needs to be installed. It is recommended that some care go into designing header files so that no more are installed than necessary.
- HD_INSTALL_HELP: Help/documentation files to be installed into the top-level help/ directory.
- HD_INSTALL_LIBRARIES: Libraries to be installed into the top-level lib/ directory.
- HD_INSTALL_PERL_LIBS: Perl libraries to be installed into the top-level lib/perl directory.

- HD_INSTALL_PERL_SCRIPTS: Perl scripts to be installed into the top-level scripts directory (currently the same as the top-level bin/ directory). At install time, Perl scripts will be edited to make sure that they use the version of Perl specified in the LHEA_PERL environment variable.
- HD_INSTALL_PFILES: Parameter files to be installed into the top-level syspfiles/ directory.
- HD_INSTALL_REFDATA: Data files to be installed into the top-level refdata/ directory.
- HD_INSTALL_TASKS: Compiled tasks to be installed into the top-level bin/ directory.
- HD_INSTALL_SHELL_SCRIPTS: Shell scripts to be installed into the top-level scripts directory (currently the same as the top-level /bin directory).

All items specified in the above macros will also be installed automatically as part of the "publish" step. In addition, the publish step publishes the items listed in the following macros:

- HD_PUBLISH_HEADERS: C and/or C++ header files to be published into the local build include/ directory. Not every header file necessarily needs to be published.
- HD_PUBLISH_HELP: Help/documentation files to be published into the local build help/ directory.
- HD_PUBLISH_LIBRARIES: Libraries to be published into the local build lib/ directory.
- HD_PUBLISH_PERL_LIBS: Perl libraries to be published into the local build lib/perl directory.
- HD_PUBLISH_PERL_SCRIPTS: Perl scripts to be published into the local build scripts directory (same as the local build tasks directory). At publish time, Perl scripts will be edited to make sure that they use the version of Perl specified in the LHEA_PERL environment variable.
- HD_PUBLISH_PFILES: Parameter files to be published into the local build syspfiles/ directory.
- HD_PUBLISH_REFDATA: Data files to be published into the local build refdata/ directory.
- HD_PUBLISH_TASKS: Compiled tasks to be published into the local build bin/ directory.
- HD_PUBLISH_SHELL_SCRIPTS: Shell scripts to be published into the local build scripts directory (same as the local build tasks directory).

3.3.5 Macros Pertaining To Subdirectories

Subdirectories into which the current Makefile should recurse when performing all standard actions (default, all, install, publish, clean, distclean) can be specified in the HD_SUBDIRS macro.

Chapter 4

HEAdas Error Handling Facility

4.1 Introduction

The heautils library contains the HEAdas error handling functions, which provide a means by which calling code can set and clear error conditions, as well as manage supporting information about errors. When an error condition is first encountered, a call to the HDerror_throw function sets the error state of the error handler, and adds an optional message. Subsequent calls to the HDerror_hint function can be used to place additional messages on the error stack. Each of these can produce an error message containing the file name and line number where the error occurred. When used, this feature in effect provides a stack trace of the error, but without using a debugger. The HDerror_reset function can be used to reset the error handler to a non-error condition. In this case, the stack is erased, and no error code is retained by the stack.

In addition, the HEAdas error facility provides a means of establishing default error messages for error codes. Several error ranges already exist within HEAdas. For example, error numbers between 1 and 999 are associated with Cfitsio errors, while -3999 to -3000 are associated with PIL. Each of these error codes has an associated standard error message. The HEAdas error handler contains a map of each error code to its message. Also there is a means to add new error maps, in order to provide standard error messsages for new software components within different numeric code ranges. These maps may be used as a task exits to print the standard message if no custom message is available.

For convenience, several macros which wrap these functions are also provided. The macros HD_ERR_SET, HD_ERR_THROW, and HD_ERR_HINT use the functions HDerror_throw and HDerror_hint to do their work. There were two reasons for defining these macros. One is that the macros can check their status arguments before calling their underlying functions, thus eliminating the overhead of a function call unless an error actually occurs. The second is that the functions HDerror_throw and HDerror_hint have arguments which can be used to give the location (source file and line number) of the error. The macros listed above do not take these arguments, but use the __FILE__ and __LINE__ macros to create them when they call the appropriate error function.

4.2 HEAdas Error Handling API

The HEAdas Error Handling API contains a number of functions and macros. The functions are described first, but in practice the macros should be used whenever possible, because they are easier to use and offer performance advantages. Central concepts are that each error message has an associated integer error number, and that the error handler as a whole also has an error number, which corresponds to the first error which was encountered.

1 int HDerror_get(void)

Returns the current value of the error handler's integer error status variable.

2 int HDerror_throw(const char * msg, const char * fileName, int line, int errNum)

This function uses the errNum argument to determine if an error has occurred, and if one has, changes the state of the error handler as appropriate to include the given information about the error. The argument msg is a string describing the error. If it is NULL no text message will be added. Arguments fileName and line are the file name and line number where the error was thrown. If fileName is NULL this information will not be included. The argument errNum is used in conjunction with the error handler's internal error status as follows: if either errNum or the error handler's internal status is non-zero, the information about the error will be added to the error handler's error message stack. If the error handler's internal status is zero, it will be set equal to errNum. Otherwise, the error handler's internal status will not be changed.

This function cannot be used to reset the error handler's internal status to zero after an error. To do this, use HDerror_reset().

3 int HDerror_hint(const char * msg, const char * fileName, int line, int errNum)

This function is similar to HDerror_throw, described above. The arguments given may be used to add to the description of an error. The difference between the two functions is that HDerror_hint never affects the overall error status of the error handler. HDerror_hint may thus not be used to create an error condition, only to comment on an existing error condition.

4 int HDerror_reset(void)

Resets the error handler's status to HD_OK and clears the error message stack.

5 int HDerror_get_stack(const char** stack)

This function returns a NULL-terminated array of const char* pointers which contains the current stack of messages. The standard HEAdas shutdown code which executes just before a task exits will print this stack to stderr if the task exits with non-zero status.

6 void HDerror_dump_silence(int silent)

Sets a silent mode which suppresses all reporting of errors. Calling it with a non-0 argument activates silent mode, while calling it with an argument of 0 sets non-silent (normal) mode. Note that silencing error reporting does not prevent error messages from being added to the error stack; rather it merely prevents these messages from being displayed.

This function should not be used in general. It is present only for the benefit of very unusual tools which return a non-0 exit status to indicate something other than an error. For example, ftdiff uses a non-0 status to indicate that it detected differences between the two input files.

7 int HDerror_dump_is_silent(void)

Returns the current silent mode of the error reporting mechanism. A non-0 value indicates errors are silenced, while a value of 0 indicates errors will be reported.

8 HD_OK

Macro whose value is 0, used throughout HEAdas software to indicate normal (non-error) status.

9 HD_ERROR_GET()

Macro which simply calls HDerror_get(). This is provided mainly for completeness and to allow a consistent look and feel if other similar macros are used.

10 HD_ERROR_THROW(MSG, STATUS)

This macro is provided for more convenient access to the function HDerror_throw(). This macro simply calls the function, using MSG for the input argument msg, STATUS for the input argument errNum, and filling in the fileName and line arguments using ANSI C's __FILE__ and __LINE__ macros.

11 HD_ERROR_SET(STATUS)

This macro is provided for more convenient access to the function HDerror_throw(). This macro simply calls the function, using NULL for the input argument msg, STATUS for the input argument errNum, and filling in the fileName and line arguments using ANSI C's __FILE__ and __LINE__ macros.

12 HD_ERROR_HINT(MSG, STATUS)

This macro is provided for more convenient access to the function HDerror_hint(). This macro simply calls the function, using MSG for the argument msg, STATUS for the argument errNum, and filling in the fileName and line arguments using ANSI C's __FILE__ and __LINE__ macros.